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S-430i™

Basic D scription

FANUC Robotics' S-430*i* line of robots is designed for maximum flexibility, performance and reliability in automotive, material handling and general industries applications and is supported by our extensive service and parts network. The S-430's compact design features a large work envelope (including flip over) and capacity for high speeds and heavy payloads.

S-430i, the Solution for:

- Automotive spot welding and general assembly
- General industrial applications
- Part transfer
- Material removal
- Dispensing
- Machine loading

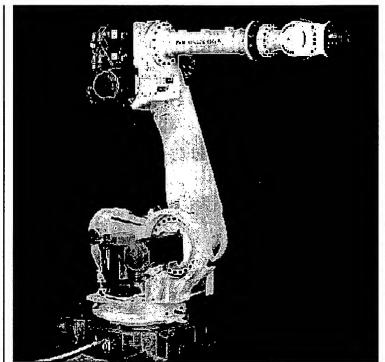
Benefits

- Large work envelope with ability to reach overhead and behind
- Slim arm and wrist assembly
- Compatible with S-420i robot applications (wrist flange and envelope)
- Proven FANUC servo drive system with fast point-to-point positioning

Features

Flexibility:

- Multiple controller type and locations
- Variety of models (S-430i family)



- Shared features from S-420 and S-420*i* series such as identical tooling faceplates
- Can reach all areas of S-420 and S-420i work envelope making replacement easy

Mechanical:

- 6 axes of motion
- Slim profile design
- Large allowable wrist moments and inertias
- Many process attachment points
- Stationary outer arm
- Precision gear drives for axes J5 and J6
- Elimination of counterweight increases available workspace
- Process/application cables routed through the arm
- No motors at wrist

Control:

 i-size (integrated or remote) cabinet

- Quick change amplifier (<5 min)
- Fast boot-up time (<30 sec)
- Easy connections to a variety of I/O

Software:

- Same look and feel as S-420 series robots
- Specific tool packages for various applications

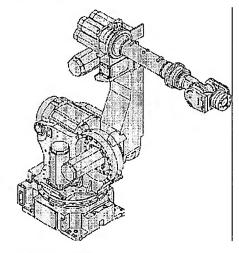
Options

- Dual internal air lines
- Three faceplate types
- Electrically insulated faceplate
- Internal I/O cables
- Harsh environment protection
- Adjustable hard stops for J1-J3
- Precision baseplate for mounting
- B-size controller cabinet

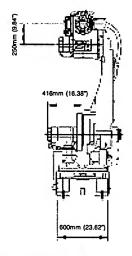
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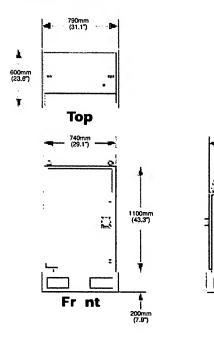
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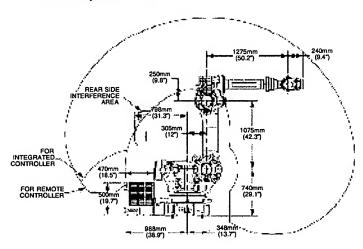
S-430iF, iW, iL Front



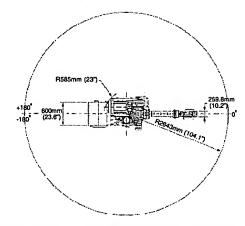
B-size Controller Option



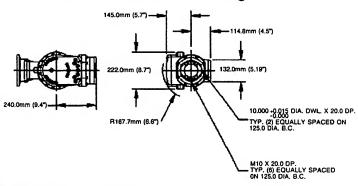
S-430iF, iW Side



S-430iF, iW Top



S-430 iF, iW, iL, iR Wrist ISO Flange

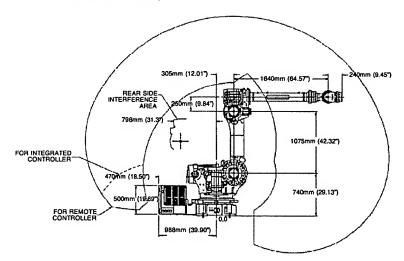


S-430*i* **Product Line** Family of S-430*i* Robots

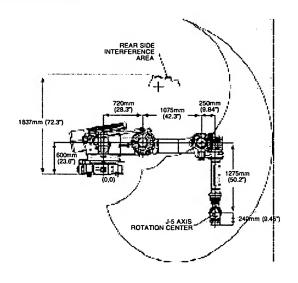
Side

Model	Payload	Purpose				
S-430 /F	130kg	Floor mount				
S-430/W	165kg	Heavy duty floor mount				
S-430/W	200kg	Extra Heavy duty floor mount Long arm floor mount				
S-430 iL	80kg					
S-430 iL	125kg	Heavy duty long arm floor mount				
S-430 /R	130kg	Rack mount				
S-430 /R	165kg	Heavy duty rack mount				
S-430 IU	130kg	Invert mount				

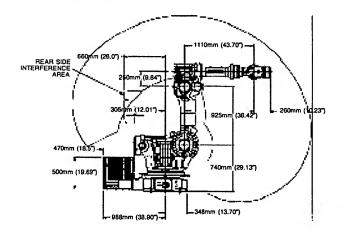




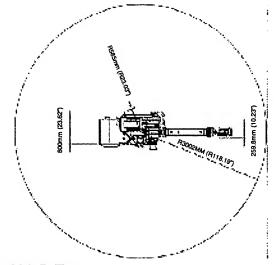
S-430iR Side



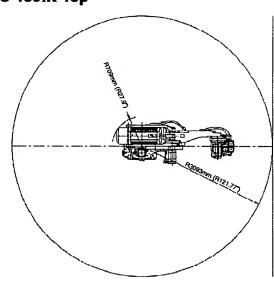
S-430*i*W/200kg Side



S-430*i*L Top



S-430*i*R Top



S-430iW/200kg, iU Top

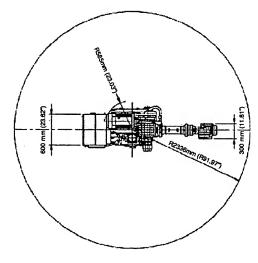
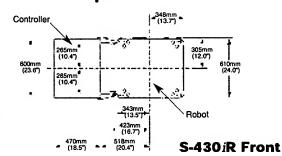


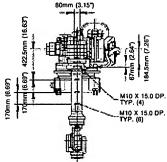
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S-430iU Side

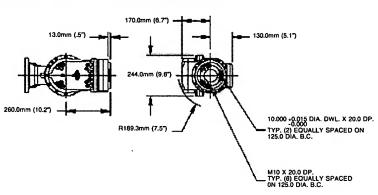
348mm (13.70°) 1110mm (43.70°) 660mm (26.00°) A = Robot can move through this area, but can not rest in this area

S-430i Fo tprint

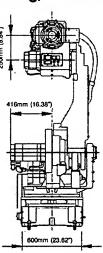




S-430iW/200kg, iU Wrist ISO Flange



S-430iW/200kg, iU Front



S-430i Specifications

Specification	IS	S-430 <i>i</i> F	S-430/W	S-430 <i>i</i> W	S-430 <i>i</i> L	S-430 <i>i</i> L	S-430/R	S-430 <i>i</i> R	S-430 <i>i</i> U	
Payload		130kg (286 lbs)	165kg (383 lbs)	200kg (441 lbs) 80kg (178 lb	s) 125kg (275	bs) 130kg (288	lbs) 165kg (364	(bs) 130kg (2	286 lbs
Reach		2643mm (1047)	2643mm (104")	2336mm (92")	3002mm (1187)	3002mm (118")	3093mm (122")	3093mm (122")	2336mm (92°)	_
Interference radiu	ıs	R585mm	R585mm	R585mm	R585m	m R58	5mm R70	8mm A	08mm	R58
	J1 axis	110'/sec	105*/sec	90°/sec	130'/s	ec 10	5'/sec 11	0*/sec 1	05*/sec	90
Motion speed	J2 axis	110*/sec	105*/sec	90°/sec	130'/s	ec 10	5'/sec 9	0'/sec	90'/secsec	90
	J3 axis	100°/sec	105°/sec	90°/sec	130*/s	ec 10	5'/sec 10	0°/sec 1	05*/sec c	90
	J4 axis	210'/sec	130'/sec	110°/sec	200'/s	ec 170	/sec 21	0°/sec 1:	30'/sec	110
	J5 axis	150'/sec	130°/sec	110'/sec	170°/s	ec 170	/sec 15	0°/sec 1	30*/sec	110
	J6 axis	210'/sec	210'/sec	150°/sec	310°/s	ec 260	/sec 21	0°/sec 2	0°/sec	150
Allowable wrist	J4 axis	70kgfm	93kgfm	130kgfm	60kg	fm 60	kgfm 70	kgfm	93kgfm	₇
load moment	J5 axis	70kgfm	93kgfm	130kgfm	60kg	im 60	kgfm 70	kgfm	93kgfm	一,
	J6 axis	35kgfm	46kgfm	70kgfm	35kg	fm 35		kgfm	46kgfm	
Allowable wrist	J4 axis	417kgcm²	900kgcm²	1200kgcm ²	600kgcm²	600kgcm ²	417kgcm²	900kgcm²	417kgcm²	
load inertia	J5 axis	417kgcm²	900kgcm²	1200kgcm ²	600kgcm²	600kgcm ²	417kgcm²	900kgcm²	417kgcm²	
	J6 axis	104kgcm²	450kgcm²	600kgcm ²	200kgcm²	230kgcm²	104kgcm²	450kgcm²	104kgcm²	
Repeatability	•	±0.3mm	±0.3mm	±0.3mm	±0.3mm	±0.3mm	±0.3mm	±0.3n		_
Mounting method		Upright	Upright	Upright	Uprig	ht Up	right Uj	right	Upright	<u> </u>
Mechanical brake	3	All axes	All axes	All axe			+	ll axes	All axes	
Weight		1300kg	1300kg	1300kg	1300		300kg 1600kg	1600kg	1300)ka

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Literature Request 1-800-47-ROBOT

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